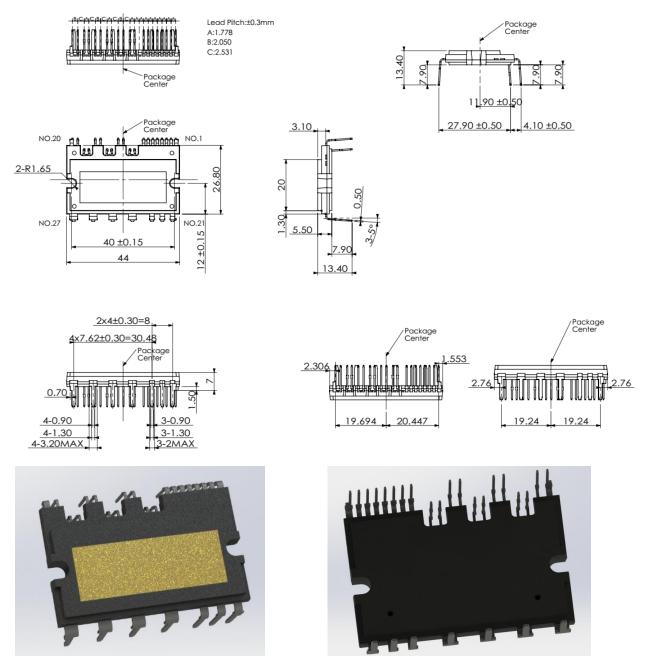
# Compact - IPM ID40FFX60U3S\_B

# Features

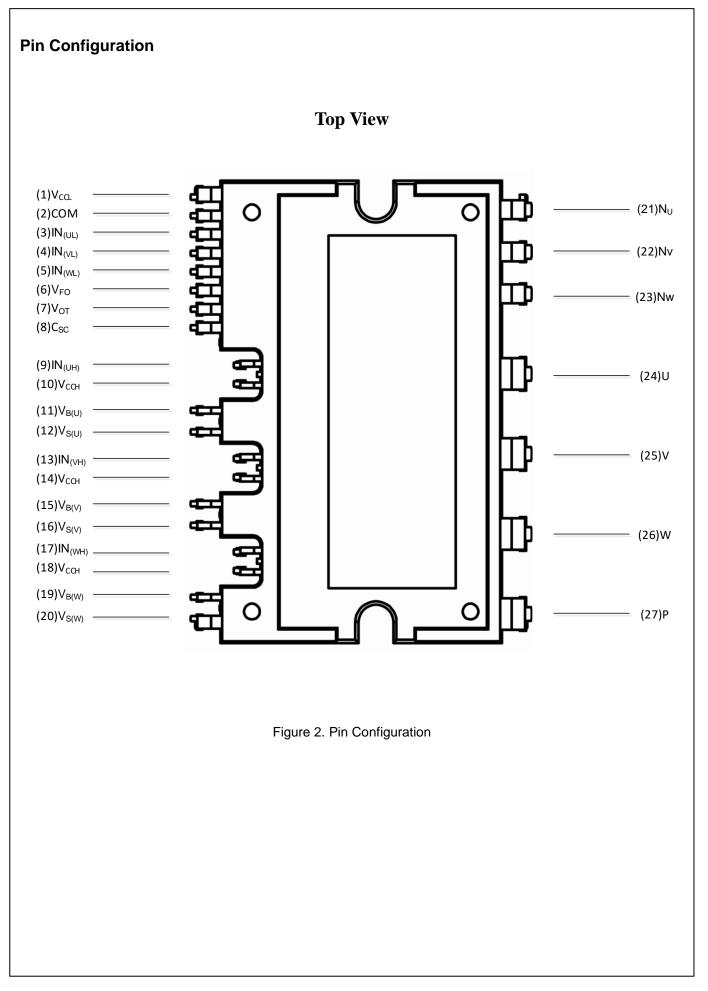
- UL 1557 Certified.
- Adopt the latest trench IGBT technology to get a good overall loss trade-off.
- Open Emitter on N terminal for low cost current sensing application.
- Matched propagation delay and arm shooting through prevention.
- Built-in bootstrap diodes with current limiting resistor.
- Provide a fault signal (FO pin) and shut-off internal IGBT when suffer S.C. and under-voltage faulty event.
- Provide Temperature output by analog signal.
- Provided Over temperature protection.
- RoHS compatible.



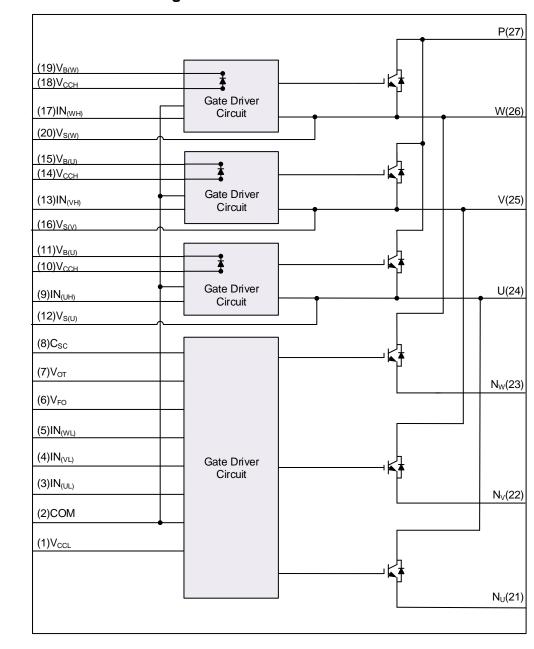
# **Table1: Pin Descriptions**

No.	Symbol	Pin Description
1	V <sub>CCL</sub>	Low-Side Common Bias Voltage for IC and IGBTS Driving
2	СОМ	Common Supply Ground
3	IN <sub>(UL)</sub>	Signal Input Terminal for Low-side U Phase
4	IN <sub>(VL)</sub>	Signal Input Terminal for Low-side V Phase
5	IN <sub>(WL)</sub>	Signal Input Terminal for Low-side W Phase
6	V <sub>FO</sub>	Fault Output Terminal
7	V <sub>OT</sub>	Temperature output
8	C <sub>SC</sub>	Short-Current Detection Input
9	IN <sub>(UH)</sub>	Signal Input Terminal for High-side U Phase
10	V <sub>CCH</sub>	High-Side Common Bias Voltage for IC and IGBTS Driving
11	V <sub>B(U)</sub>	High-Side Bias Voltage for U-Phase IGBT Driving
12	V <sub>S(U)</sub>	High-Side Bias Voltage Ground for U-Phase IGBT Driving
13	IN <sub>(VH)</sub>	Signal Input Terminal for High-side V Phase
14	V <sub>CCH</sub>	High-Side Common Bias Voltage for IC and IGBTS Driving
15	V <sub>B(V)</sub>	High-Side Bias Voltage for V-Phase IGBT Driving
16	V <sub>S(V)</sub>	High-Side Bias Voltage Ground for V-Phase IGBT Driving
17	IN <sub>(WH)</sub>	Signal Input Terminal for High-side V Phase
18	V <sub>CCH</sub>	High-Side Common Bias Voltage for IC and IGBTS Driving
19	V <sub>B(W)</sub>	High-Side Bias Voltage for W-Phase IGBT Driving
20	V <sub>S(W)</sub>	High-Side Bias Voltage Ground for W-Phase IGBT Driving
21	Nu	Negative DC-Link Input Terminal for U Phase
22	Nv	Negative DC-Link Input Terminal for V Phase
23	Nw	Negative DC-Link Input Terminal for W Phase
24	U	Output Terminal for U Phase
25	V	Output Terminal for V Phase
26	W	Output Terminal for W Phase
27	Р	Positive DC – Link Input

(see figure 2, next page)



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# The IPM Internal Block Diagram

Figure 3. IPM Internal Block Diagram

#### Application:

- Short-circuit current protection AC 100~240Vrms class 3 phase output for low power motor control.
- Household electric appliances such as air conditioners, washing machines, refrigerators, etc..,
- Low power industrial servo drives applications such as sewing machine, treadmill, etc...

# **MAXIMUM RATINGS** (T<sub>j</sub> = $25^{\circ}$ C)

### **INVERTER PART**

Item	Symbol	Min.	Max.	Unit
Between collector to emitter voltage	V <sub>CES</sub> (IGBT)	-	600	V
Supply voltage P-N	V <sub>PN</sub>	-	450	V
Supply voltage (surge) P-N	V <sub>PN (surge)</sub>	-	500	V
Each IGBT collector current	± I <sub>C</sub> (Tc = 25℃)	-	40	А
Each IGBT collector current (peak)	± I <sub>CP</sub> (Tc = 25℃, pulse)	-	80	А
Collector dissipation	$P_C$ (Tc = 25°C, per one chip)	-	108	W
Junction temperature	Tj (Note 1)	-	+150	°C

Note 1: Power chip in IPM is qualified for 175°C operation. But overall junction temperature should be limited by  $T_j \le$  125°C (@ Tc  $\le$ 

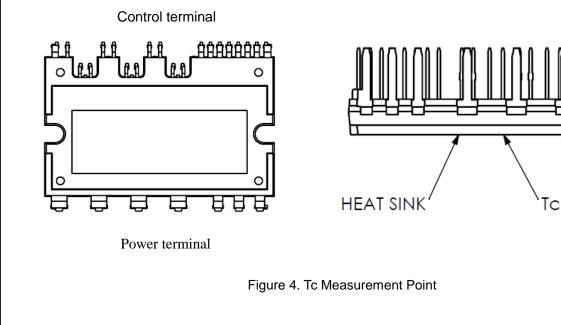
100°C) to fit long term reliability requirement.

## **CONTROL PART**

Item	Symbol	Min.	Max.	Unit
Driver IC supply voltage	Vcc	-0.3	20	V
P - side floating supply voltage	V <sub>B(u)S(u)</sub> , B(V)S(V), B(W)S(W)	-0.3	20	V
Current sensing input voltage	V <sub>SC</sub>	-0.3	Vcc+0.3	V
Logic input voltage	$IN_{(UH)}, IN_{(VH)}, IN_{(WH)},$ $IN_{(UL)}, IN_{(VL)}, IN_{(WL)}$	-0.3	Vcc+0.3	V
Fault output voltage	V <sub>FO</sub>	-0.3	Vcc+0.3	V
Fault output current	I <sub>FO</sub>	-	1	mA

# TOTAL SYSTEM

Item	Symbol	Min.	Max.	Unit
Module case operating temperature	Tc	-40	+125	°C
Storage temperature	T <sub>stg</sub>	-40	+125	°C
Isolation voltage (60Hz Sinusoidal, AC 1 minute, pins to heat-sink plate)	V <sub>iso</sub>	-	2500	Vrms



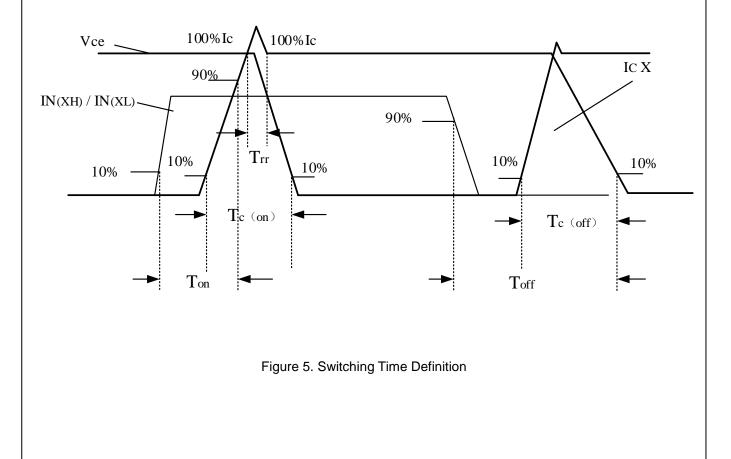
## THERMAL RESISTANCE

Item	Symbol	Condition	Min.	Тур.	Max.	Unit
Junction to case thermal	R <sub>th(j-c)Q</sub>	IGBT part (1/6)	-	1.15	-	°C∕W
resistance	R <sub>th(j-c)F</sub>	FWD part (1/6)	-	1.93	-	C/VV

ELECTRICAL CHARACTERISTICS (Tj = 25 °C)

#### **INVERTER PART**

Item	Symbol	Condition	Min.	Тур.	Max.	Unit
Collector-emitter saturation voltage	V <sub>CE (sat)</sub>	$ \begin{array}{ccc} V_{CC} = & V_{B(U)S(U), \ B(V)S(V), \ B(W)S(W)} = \\ 15V, \ I_C = 40A, \ V_{SC} = 0V \end{array} \end{array} \  \  T_j \!\!=\!\!25^{\circ}\! \mathbb{C} \label{eq:VC} $	-	1.60	-	V
FWD forward voltage drop	VF	T <sub>j</sub> =25°C, - I <sub>C</sub> = 40A	-	1.75	-	V
	$T_{on}$	V <sub>D</sub> = 300V,	-	1.10	-	
Switching times	T <sub>c(on)</sub>	$V_{CC} = V_{B(U), B(V), B(W)} = 15V,$	-	0.30	-	]
(Fig. 5)	T <sub>off</sub>	$I_{C} = 40A, T_{j} = 25^{\circ}C,$	-	1.30	-	μS
(19.3)	T <sub>c(off)</sub>	V <sub>IN</sub> = 5V <> 0V,	-	0.15	-	
	T <sub>rr</sub>	$V_{SC} = 0V$ , Inductive Load	-	0.12	-	
Collector-emitter cut-off current	I <sub>CES</sub>	V <sub>CE</sub> =V <sub>CES</sub>	-	-	1	mA

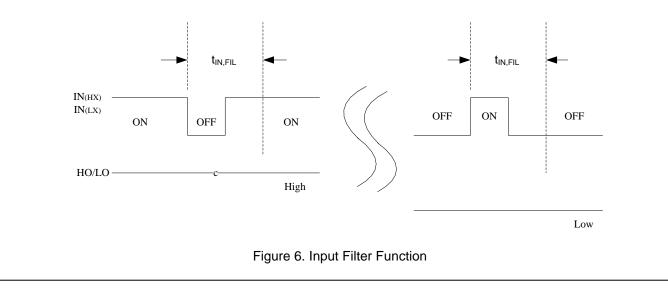


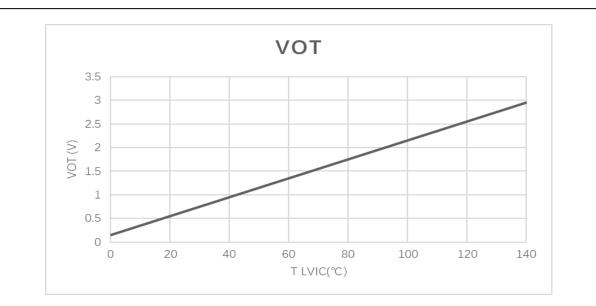
# **CONTROL PART** ( $T_j = 25^{\circ}C$ )

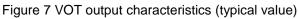
Item	Symbol	Condition	Min.	Тур.	Max.	Unit
IN <sub>(UH, VH, WH)</sub> , IN <sub>(UL,VL,WL)</sub> ON threshold voltage	V <sub>th(on)</sub>		-	-	3.0	V
IN <sub>(UH, VH, WH)</sub> ,IN <sub>(UL,VL,WL)</sub> OFF threshold voltage	V <sub>th(off)</sub>		0.8	-	-	V
IN <sub>(UH, VH, WH)</sub> input bias current	I <sub>IN(UH, VH</sub> , WH)(HI)	VIN(UH, VH, WH) = 3.3V	-	-	660	μA
	I <sub>IN(UH, VH, WH)</sub> (LO)	$V_{IN(UH, VH, WH)} = 0V$	-1	-	-	μΛ
IN(UL, VL, WL) input bias current	I <sub>IN(UL, VL, WL)</sub> (HI)	$V_{IN(UL, VL, WL)} = 3.3V$	-	-	660	μA
nv(UL, VL, WL) input bias current	I <sub>IN(UL, VL, WL)</sub> (LO)	$V_{IN(UL, VL, WL)} = 0V$	-1	-	-	μΑ
Quiescent V <sub>BS</sub> supply current	I <sub>QBS</sub>	V <sub>BS</sub> =15V, V <sub>IN=</sub> 0V	-	70	120	μA
Quiescent VCC supply current	lacc	V <sub>BS</sub> =15V, V <sub>IN=</sub> 0V	-	2	3	mA
Driver IC supply voltage	V <sub>CC</sub>		13.5	15.0	16.5	V
P - side floating supply voltage	V <sub>B(U), B(V), B(W)</sub>		13.5	15.0	16.5	V
Fault output voltage	V <sub>FOH</sub>	V <sub>CC</sub> =15V,V <sub>SC</sub> =0V(Note 2)	4.5	-	-	V
Fault output voltage	V <sub>FOL</sub>	V <sub>CC</sub> =15V,V <sub>SC</sub> =1V(Note 2)	-	-	0.8	V
Short circuit trip level	V <sub>SC(ref)</sub>	$V_{CC} = 15V, T_j = 25^{\circ}C$	0.45	0.48	0.51	V
Fault output pulse width	t <sub>FOD</sub>		60	-	-	μs
	UV <sub>CCD</sub>	Trip level	-	11.0	-	V
Supply Circuit	UV <sub>CCR</sub>	Reset level	-	12.0	-	V
Under-Voltage-Protection	UV <sub>BSD</sub>	Trip level	-	10.5	-	V
	UV <sub>BSR</sub>	Reset level	-	11.5	-	V
$IN_{(UL,\ VL,\ WL)}$ Input filter time	t <sub>IN,FIL</sub>	V <sub>IN</sub> = 0 & 5V (Note 3)	200	300	510	ns
		LVIC temperature=25℃	0.55	0.65	0.75	V
Temperature Output	V <sub>OT</sub>	LVIC temperature=120°C	2.45	2.55	2.65	V
	OT <sub>t</sub>	Trip level		150		°C
Over temperature protection	OT <sub>rh</sub>	Hysteresis of trip-reset		20		°C
VF	Bootstrap diode forward voltage	lf=10mA, Tj = 25℃	-	1.6	-	V
R	Limiting resistance	Individual resistor	-	80	-	Ohm

**Note 2:**  $V_{FO}$  output is open collector type, so this signal line should be pulled up to the +5V power supply with approximately 4.7K $\Omega$ **Note 3:** For high side PWM, IN(UH, VH, WH) pulse width must be  $\geq$  1 us.

# **Input Filter Function**







#### **RECOMMENDED OPERATION CONDITIONS**

Item	Symbol	Condition	Min.	Тур.	Max.	Unit
DC – Link Supply voltage	VD	Applied between P-N	0	300	400	V
Driver IC supply voltage	Vcc	Applied between V <sub>CC</sub> - COM	13.5	15.0	16.5	V
P - side floating supply voltage	V <sub>BS</sub>	Applied between $V_{B(u,\ v,\ w)}-V_{S(u,\ v,\ w)}$	13.5	15.0	16.5	V
Supply voltage ripple	$\Delta V_D$ , $\Delta V_{DB}$		-1	-	1	V/µs
Arm shoot-through blocking time	t <sub>dead</sub>		1	-	-	μs
PWM input frequency	f <sub>PWM</sub>	$T_C \leq 100^{\circ}C, T_j \leq 125^{\circ}C$	-	0	20	kHz
Voltage for Current Sensing	V <sub>SEN</sub>	Applied between $N_U, N_V, N_W - COM$ (Including Surge Voltage)	-4	-	4	V

## **MECHANICAL CHARACTERISTICS AND RATINGS**

Item	Condition			Тур.	Max.	Unit
Mounting torque	Mounting screw: M3	Commended () / N•m		0.7	0.8	N•m
Weight			-	15.00	-	g
Heat-sink flatness			0	-	150	μm

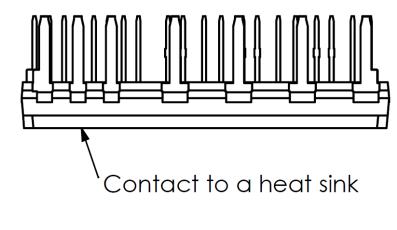
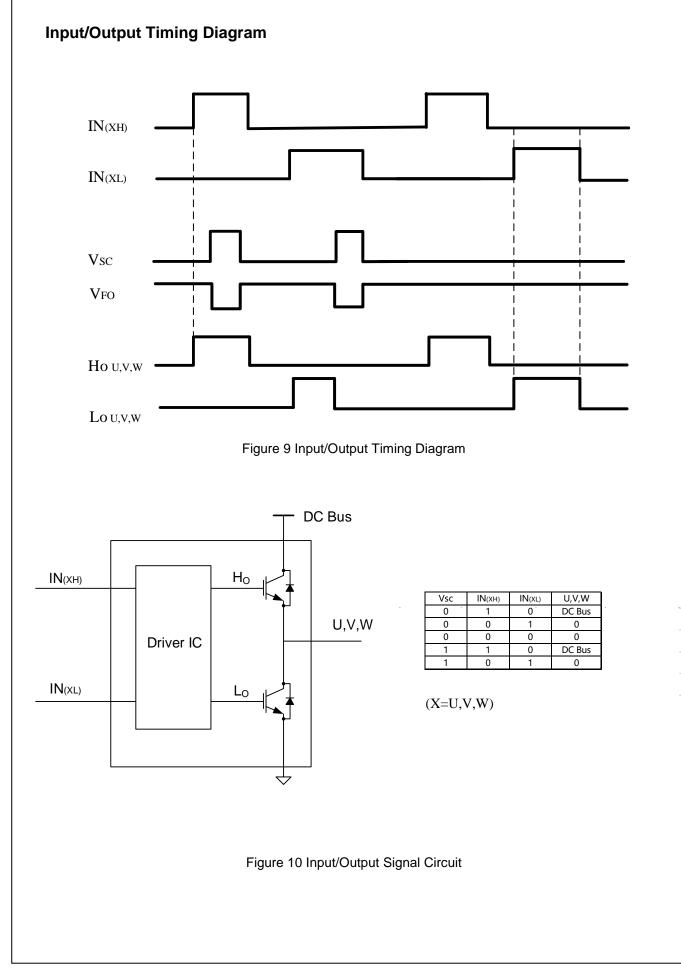
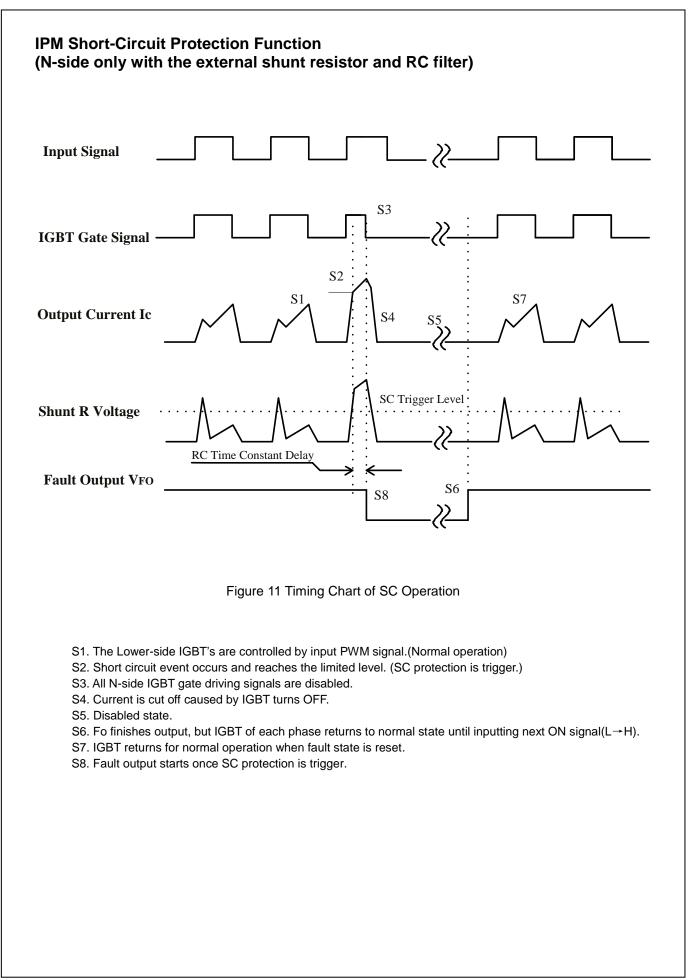


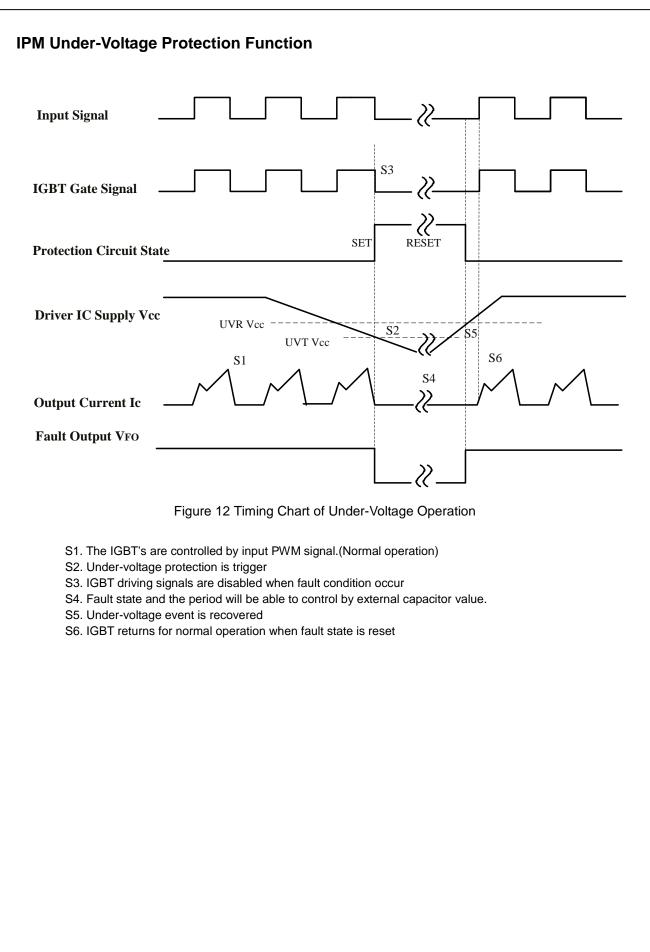
Figure 8 Measurement Location of Heat-sink Flatness

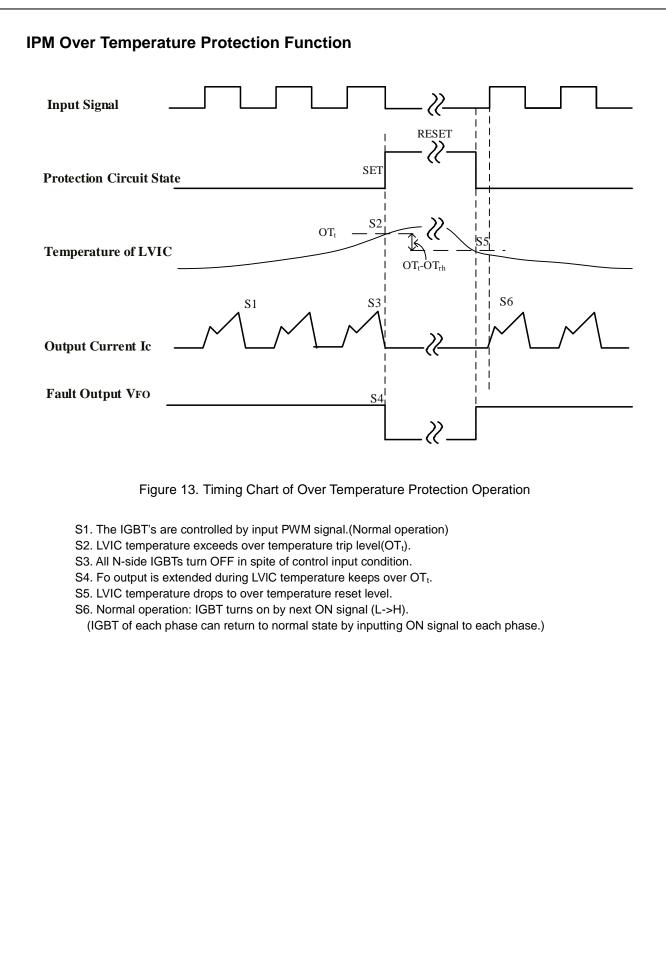
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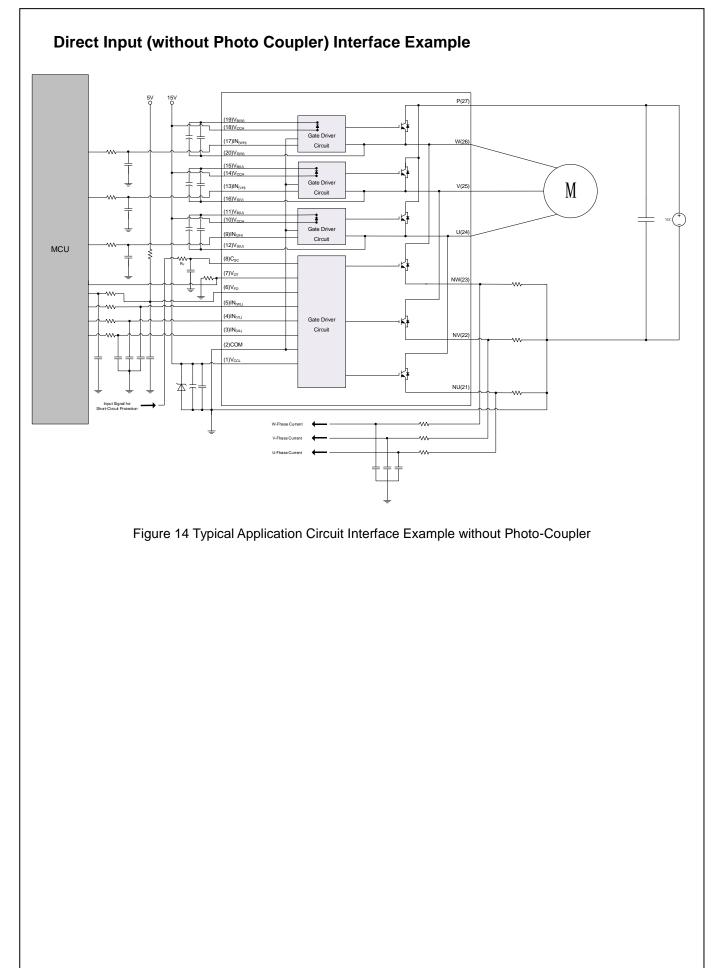


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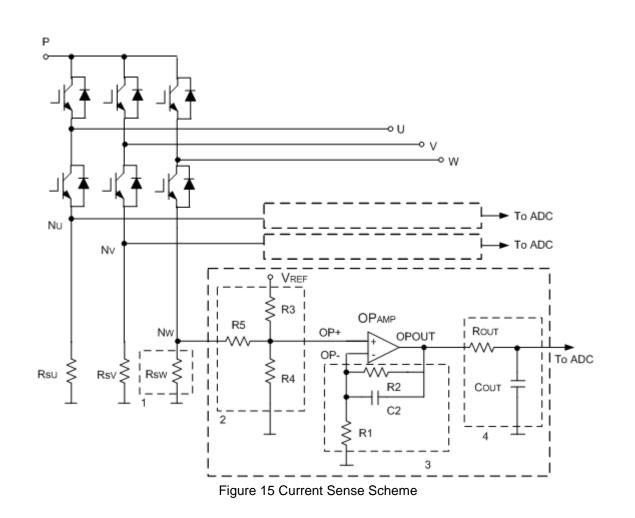








## **Current Sense Shceme**



## **Precautions on Electrostatic Electricity**

- (1) Operators must wear anti-static clothing and conductive shoes (or a leg or heel strap).
- (2) Operators must wear a wrist strap grounded to earth via a resistor of about 1 M $\Omega$ .
- (3) Soldering irons must be grounded from iron tip to earth, and must be used only at low voltages.
- (4) If the tweezers you use are likely to touch the device terminals, use anti-static tweezers and in particular avoid metallic tweezers. If a charged device touches a low-resistance tool, rapid discharge can occur. When using vacuum tweezers, attach a conductive chucking pat to the tip, and connect it to a dedicated ground used especially for anti-static purposes (suggested resistance value: 10<sup>4</sup> to 10<sup>8</sup>Ω).
- (5) Do not place devices or their containers near sources of strong electrical fields (such as above a CRT).
- (6) When storing printed circuit boards which have devices mounted on them, use a board container or bag that's protected against static charge. To avoid the occurrence of static charge or discharge due to friction, keep the boards separate from one other and do not stack them directly on top of one another.
- (7) Ensure, if possible, that any articles (such as clipboards) which are brought to any location where the level of static electricity must be closely controlled are constructed of anti-static materials.
- (8) In cases where the human body comes into direct contact with a device, be sure to wear anti-static finger covers or gloves (suggested resistance value: 10<sup>8</sup>Ω or less).
- (9) Equipment safety covers installed near devices should have resistance ratings of  $10^9\Omega$  or less.
- (10) If a wrist strap cannot be used for some reason, and there is a possibility of imparting friction to devices, use an ionizer.

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